# Trickle: Automated Infeasible Path Detection Using All Minimal Unsatisfiable Subsets



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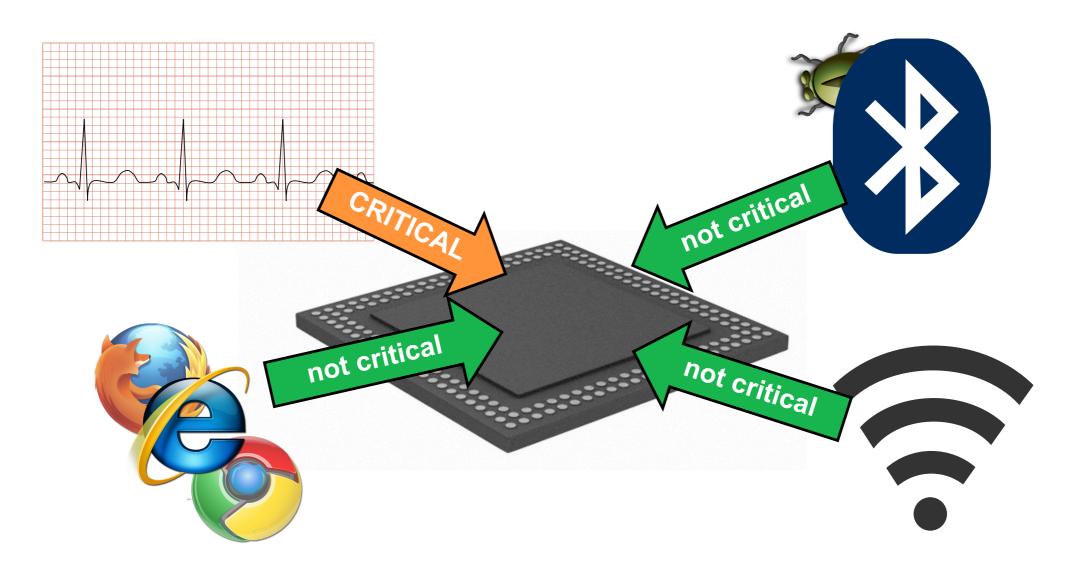






# **Motivation**

 The desire for a trustworthy kernel to build reliable mixed-criticality real-time systems





#### **Motivation**

 The desire for a trustworthy kernel to build reliable mixed-criticality real-time systems

- Using seL4 to guarantee:
  - functional correctness through formal proof

(Klein et al., SOSP 2009)

timing constraints through sound WCET analysis

(Blackham et al., RTSS 2011)

3



# **Motivation**

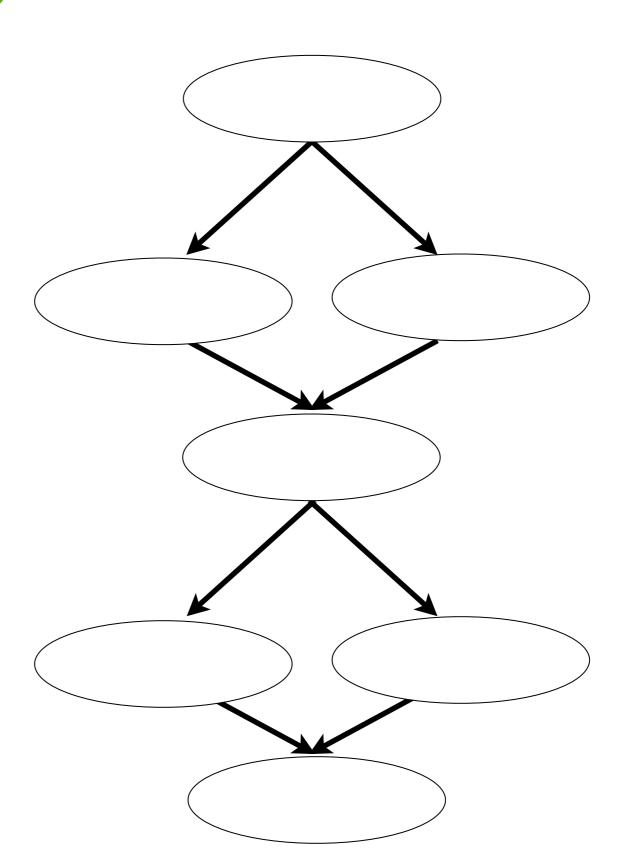
 The accuracy of WCET estimates directly affects the hardware provisioning of such systems (e.g. CPU speed) → cost

 Inaccurate WCET estimates by static analysis can be caused by infeasible paths

- By excluding culprit infeasible paths
  - → less provisioning required
  - > reduced hardware cost

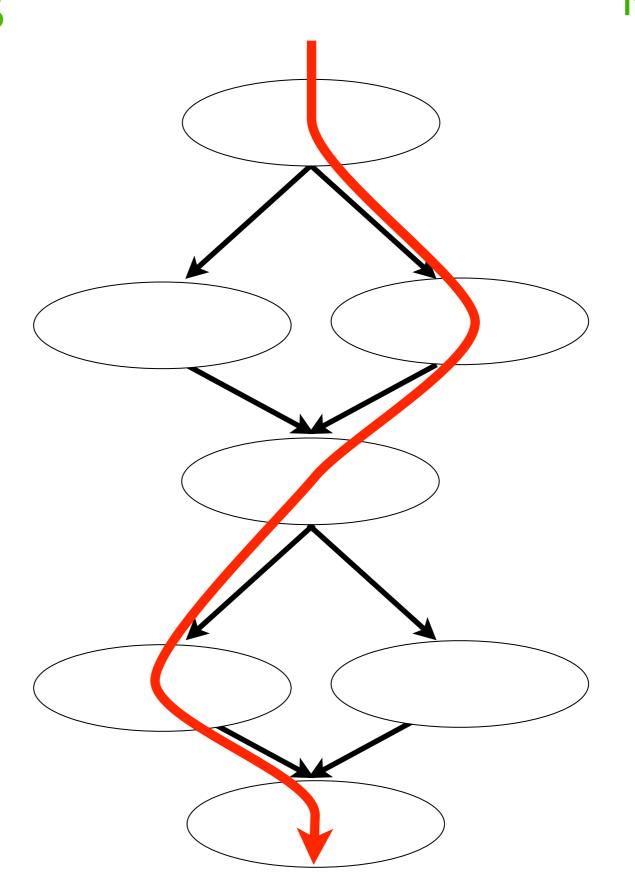


```
int f(int a)
    if ((a & 4) == 0)
    else
    if ((a & 4) == 0)
    else
```



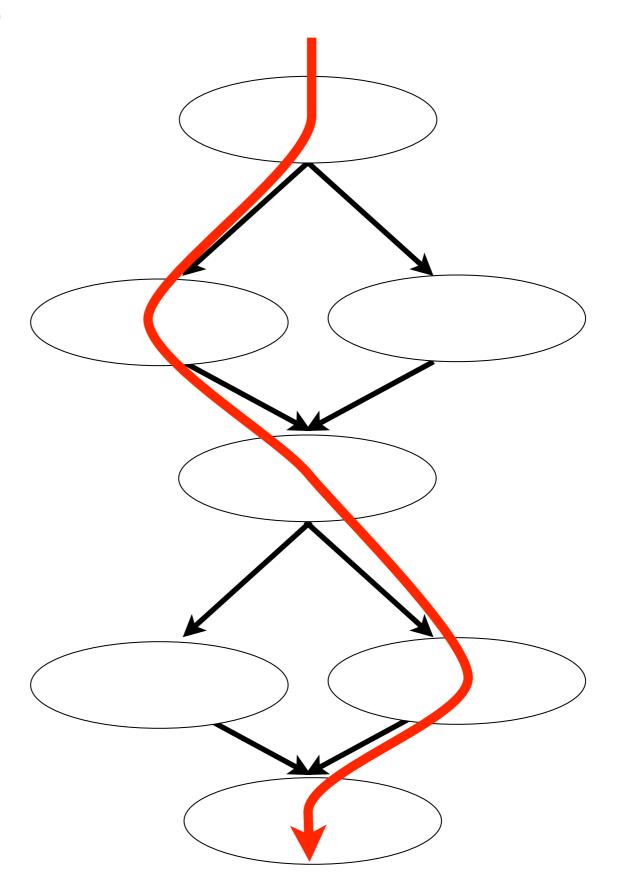


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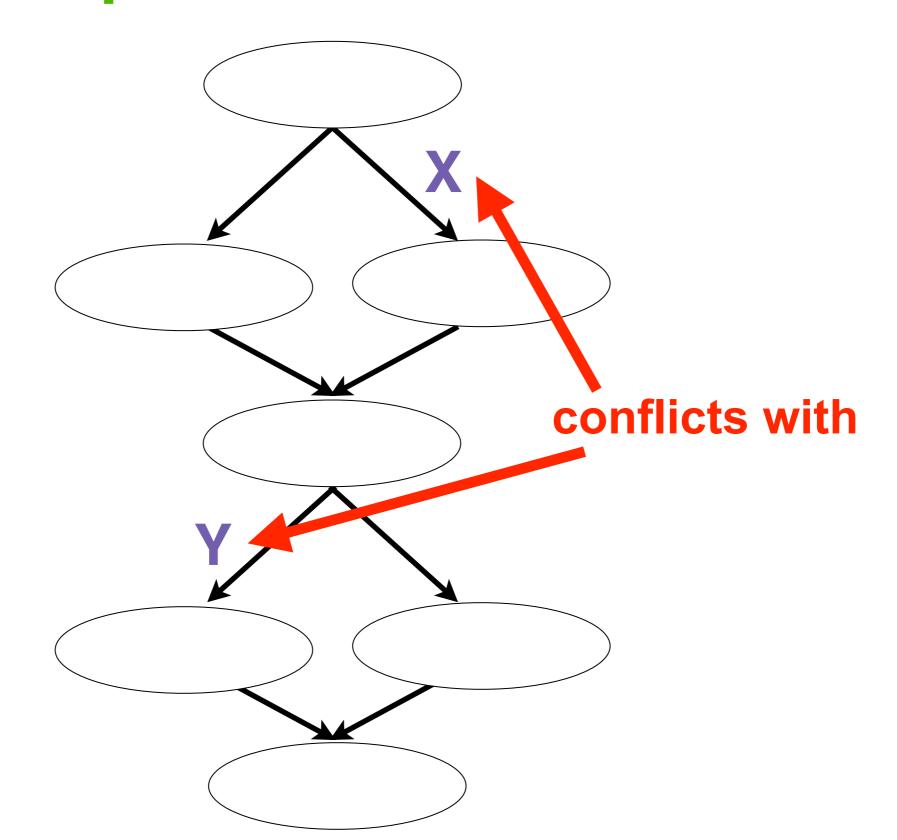




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# Background

- Chronos used to compute WCET via IPET
- Sequoll can validate manually provided infeasible path information using a model checker

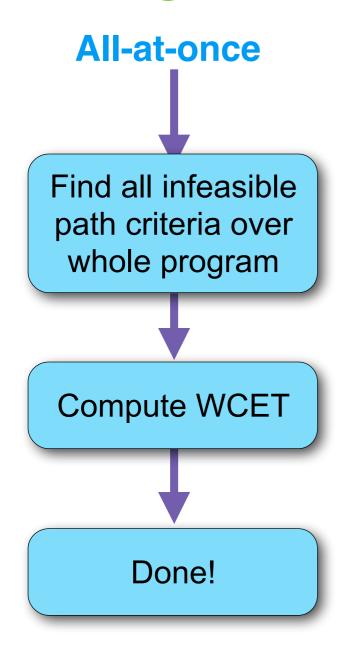
(Blackham & Heiser, RTAS 2013)

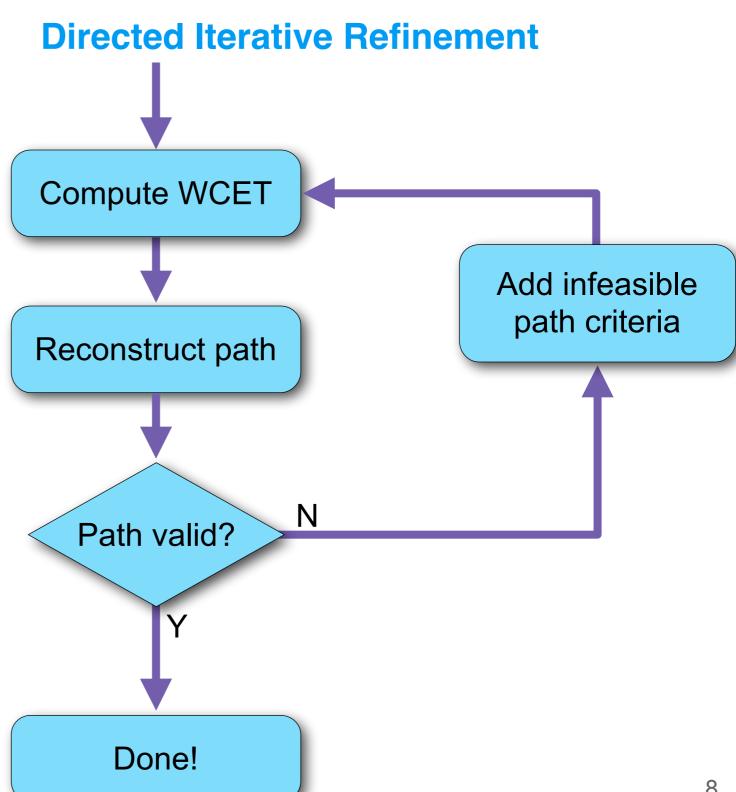
- Reduces risk of human error when specifying infeasible path information
- Can we find infeasible paths automatically?



# Finding infeasible path constraints

#### **NICTA**







# seL4 is large

- Small by microkernel standards
- Large by WCET standards

#### **C** source

~8,700 lines
316 functions
76 loops

# Binary (ARM)

~10,000 instructions

228 functions

56 loops

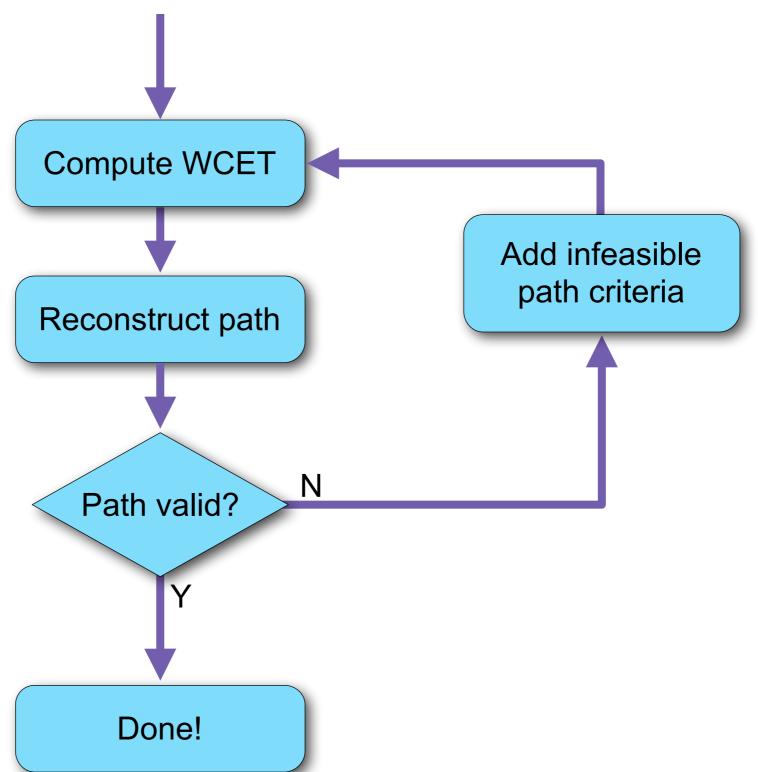
2,384 basic blocks

~400,000 basic blocks when inlined



#### Trickle: Directed Iterative Refinement







# Types of infeasible path criteria

Infeasible path criteria may arise because of:

#### local constraints

```
y = count;
if (y > 15)
    y = 15;
while (y > 0)
{
    y = y - 1;
}
```

#### global program invariants

```
// count guaranteed to be <= 15
y = count;
while
{
    y = y -
}</pre>
```



# Types of infeasible path criteria

Infeasible path criteria may arise because of:

#### local constraints

```
y = count;
if

y =
while
{
    y = y -
}
```

#### global program invariants

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// count guaranteed to be <= 15
y = count;
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# Types of infeasible path criteria

Infeasible path criteria may arise because of:

#### local constraints

# y = count; if (y > 15) y = 15; while (y > 0) { y = y - 1; }

#### global program invariants

```
// count guaranteed to be <= 15
y = count;
while (y > 0)
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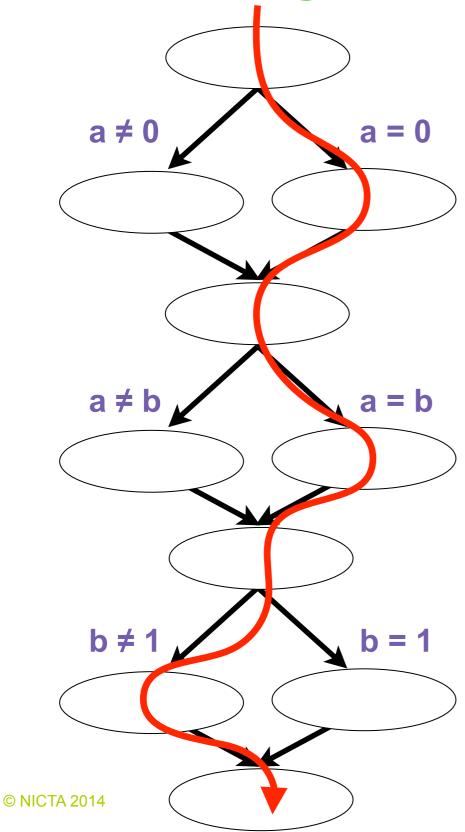
- Sequoll computes a branch condition for every conditional branch or conditional instruction, in terms of SSA variables
- Once a worst-case path is identified,
   Trickle collects all branch conditions required to execute it, as SMT expressions
- All branch conditions are given to an SMT solver to find a satisfying assignment



- If SMT solver finds a satisfying assignment, path is declared feasible\*
- If SMT solver shows that the constraints are unsatisfiable, the path is infeasible
  - → An unsatisfiable subset is returned

\* up to the limit of reasoning ability of the SMT solver and Trickle





A: a=0

**B**: a=b

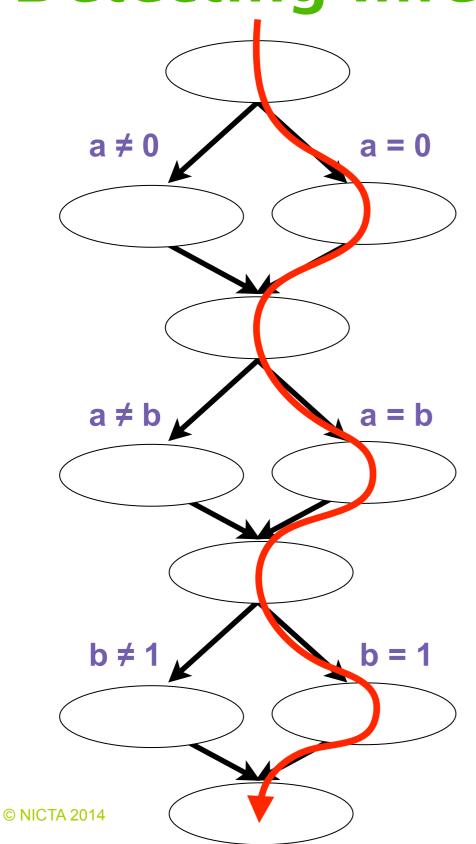
**C**: b≠1

Satisfiable!

Assignment: a=0, b=0







A: a=0

**B**: a=b

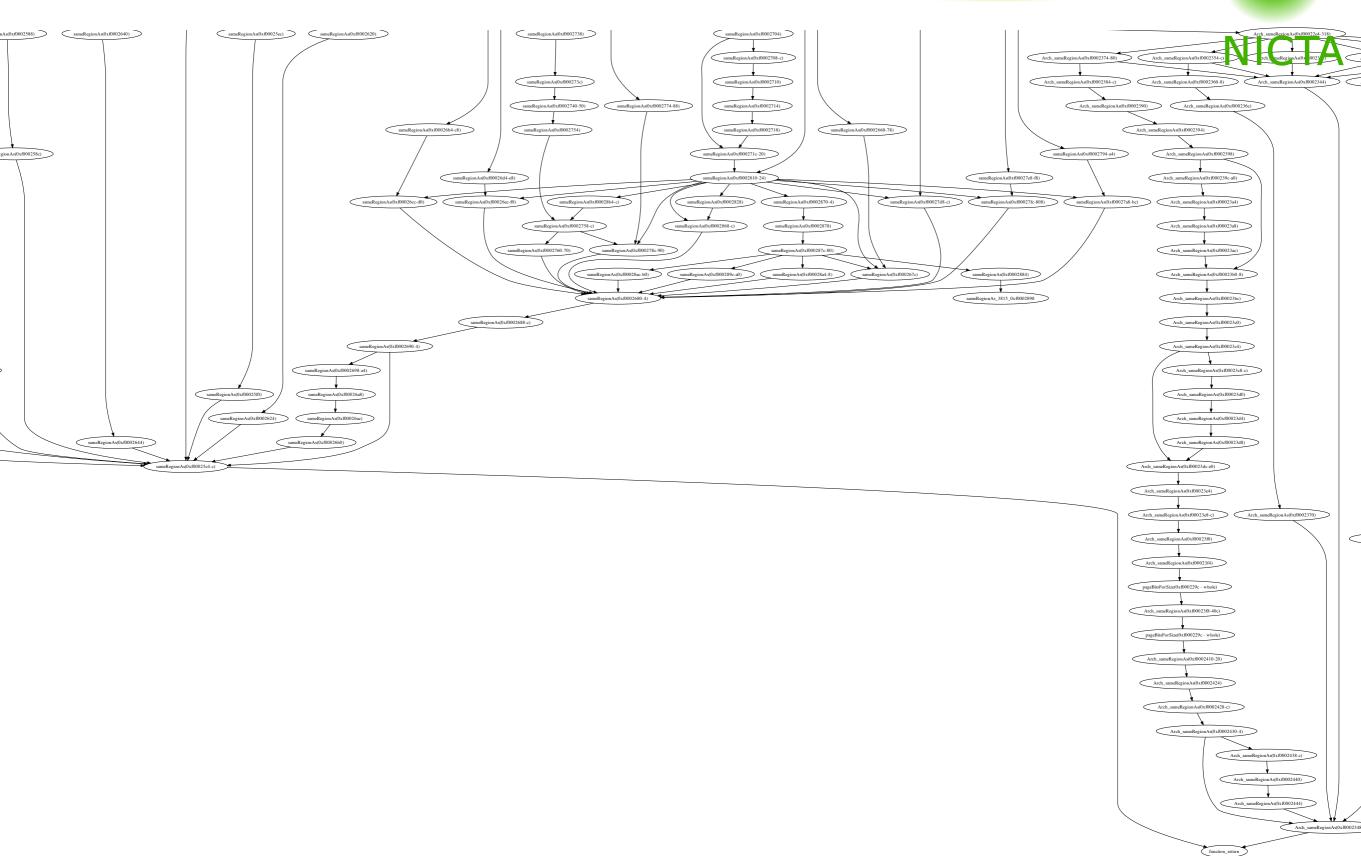
C: b=1

# Unsatisfiable \$\frac{1}{2}\$

Minimal Unsatisfiable Subset: **{A,B,C}** 

$$E_A + E_B + E_C < 3$$





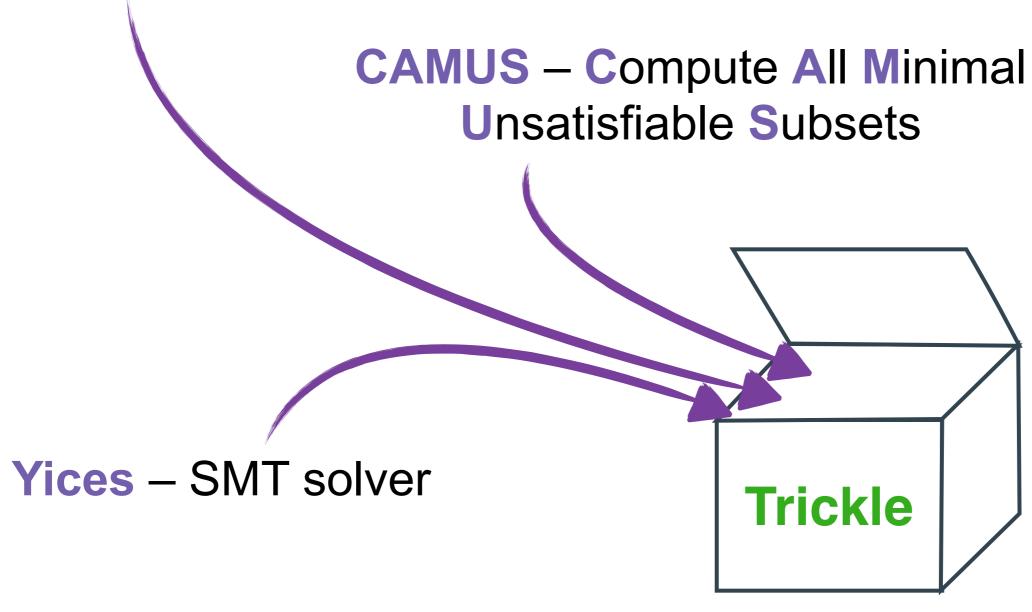


- A path may contain 1000s of instructions
- And 100s of branch constraints
- And may contain several MUSes
- SMT solvers typically only find one
- Can we reduce the number of refinement iterations?



# **Trickle: Enter CAMUS**

Sequoll – framework for analysis of compiled ARM binaries





20

# **CAMUS**

Developed by Liffiton & Sakallah (JAR 2008)

 Finds all minimal unsatisfiable subsets of a given set of constraints

→i.e. finds all infeasible path constraints along a given path



#### **CAMUS**

 The worst-case run time of the CAMUS algorithm is exponential in the number of MUSes (+ SMT solver time)

How can we prevent this?



# **CAMUS: Sliding Window**

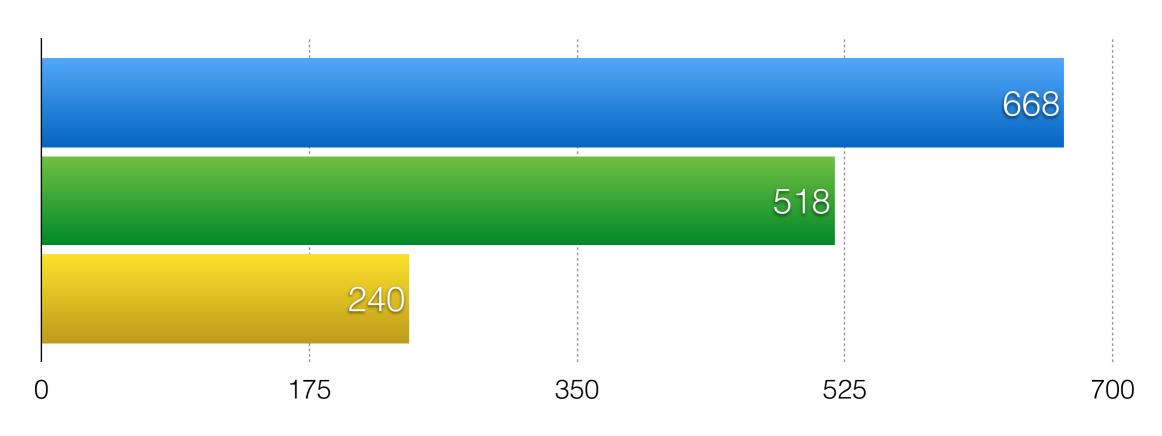
# ABCDEFGHIJKLMNO

- Try with a smaller subset of constraints first
- Choose constraints close together on path as they are more likely to conflict
- Increase size of window and repeat if no constraints found



# Results

#### Estimated worst-case execution time of seL4



000's of cycles

23

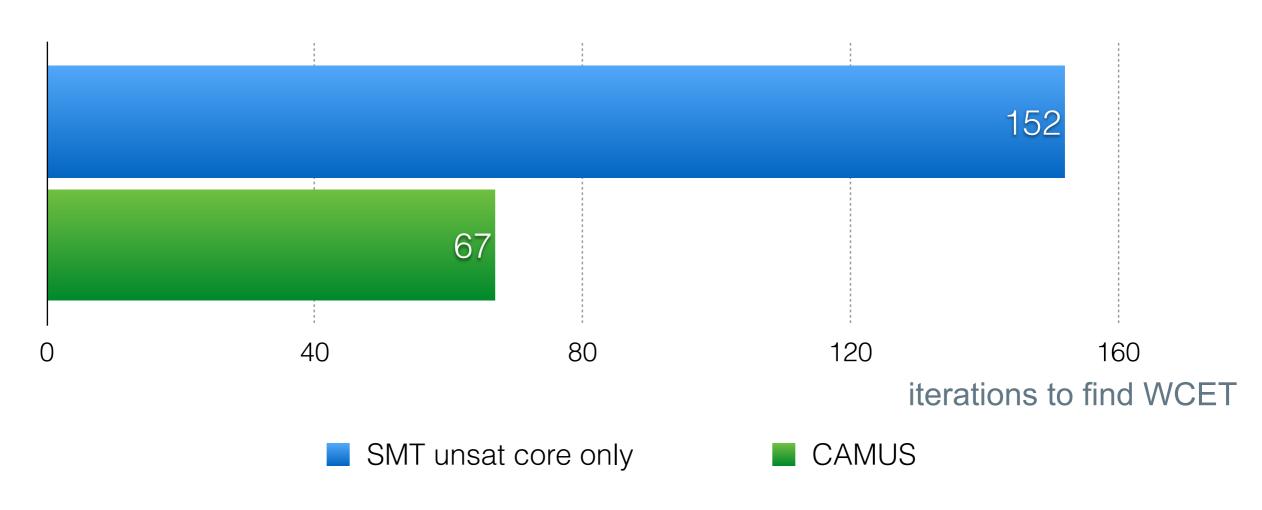
- Baseline (no infeasible path information)
- Trickle applied to baseline
- Trickle + human efforts



24

# Results

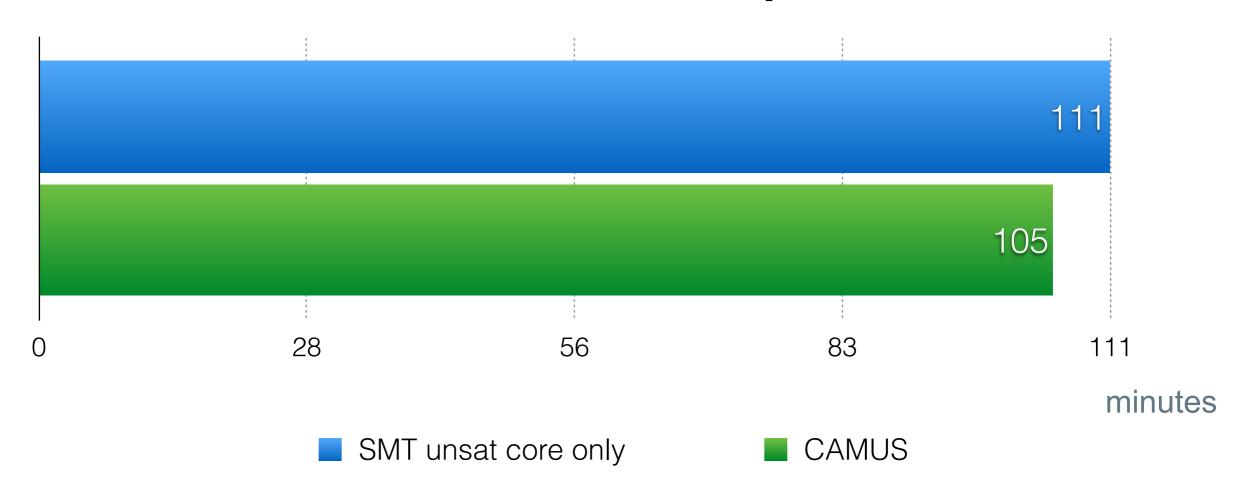
#### **Number of iterations to find WCET**





# Results

#### Difference in runtime to compute WCET\*



<sup>\*</sup> Implementation-specific compilation overheads subtracted



# Limitations

- What about loops?
  - Analysis is limited to loop-free regions of code
  - Limitation of SMT solvers
  - Limitations of IPET method
- Run time of analysis is long
  - Full analysis takes > 2 hours



# Research directions

- Integrate Trickle with proof invariants
- Find infeasible paths across loop iterations
- Improved CAMUS algorithm to avoid exponential behaviour (no need for sliding window)
- Improve memory aliasing analysis



# Summary

#### Trickle is able to:

- automatically compute infeasible path information on compiled ARM binaries
- improve WCET estimates of an IPET analysis
- reason about more interesting constraints than integer intervals (e.g. bit arithmetic)
- reduce scope for errors in WCET analysis!

#### Download it!

http://www.ssrg.nicta.com.au/software/TS/wcet-tools

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